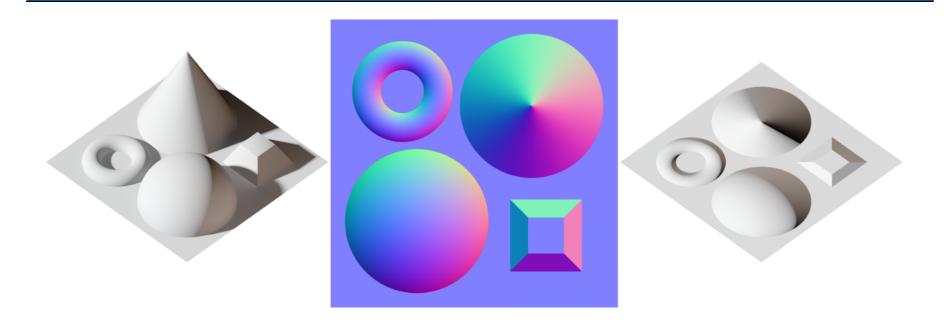
Game Technology

Lecture 6 – 28.11.2017 Bumps and Animations





Dipl-Inf. Robert Konrad Polona Caserman, M.Sc.

Prof. Dr.-Ing. Ralf Steinmetz KOM - Multimedia Communications Lab

Ludum Dare@KOM



Game Jams

- Game development contest
 - Vague theme (e.g. "Running out of Power")
 - Tight time constraints (e.g. 72 h)
 - Starting from scratch (design, assets, code, ...)
- No excuses just submit something...

Ludum Dare 40@TUD

- Sa., 2.12.2017, 9:00 Mo., 4.12.2017 (night)
- Registration (first-come-first-serve): gamejam@kom.tu-darmstadt.de
- See last Jam: https://www.kom.tu-darmstadt.de/news-events/game-jams/?no cache=1

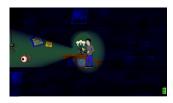




Extincti, LD#39



Guardian Stone, LD#39



Lightmare, LD39



It Came from the Dessert, LD#37



KOM Jam, 2016



Watervapor, LD#39



Dustinator X9001, LD#37



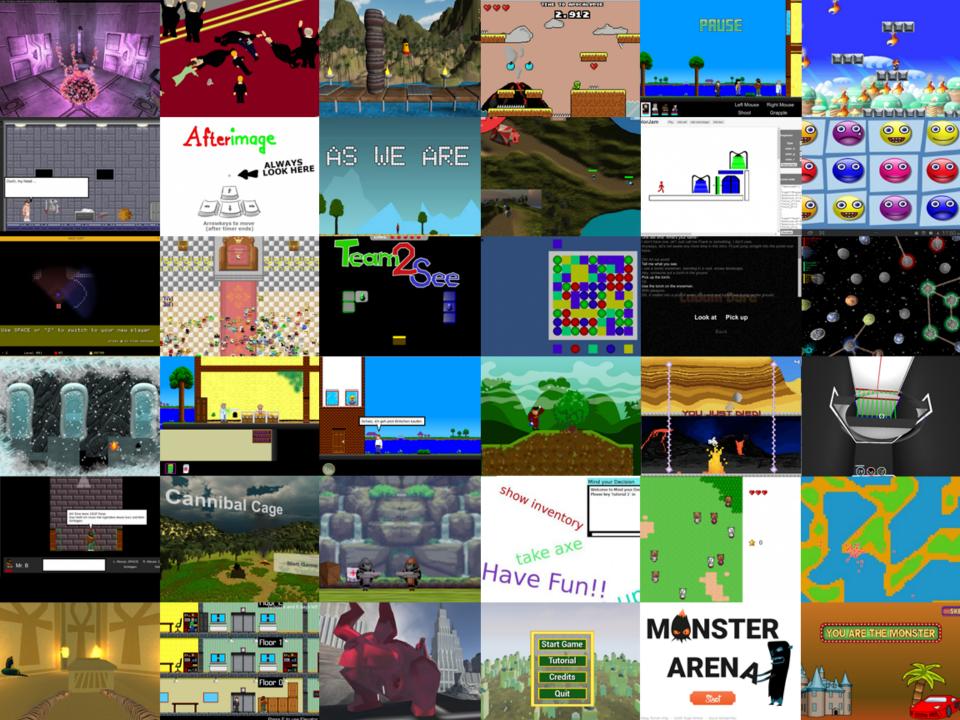
Game Jam Simulator, LD#37







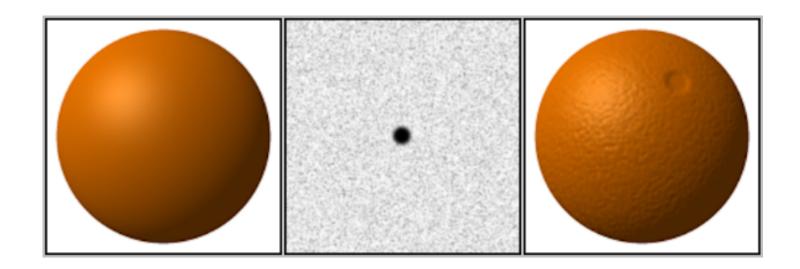




Bump Mapping



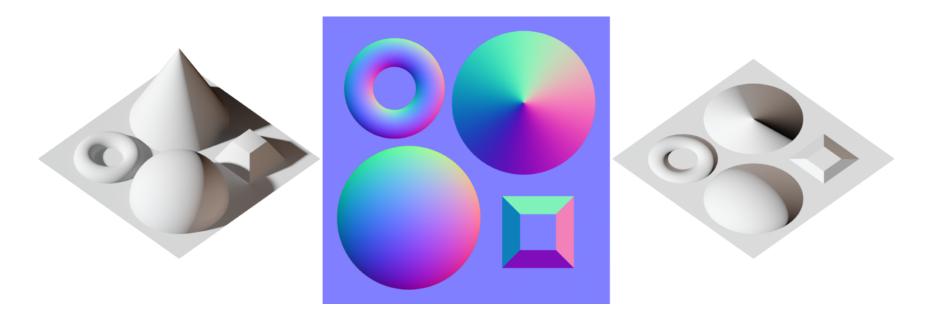
Encode information about the surface Use during shading to simulate more detail than there is



Normal Maps



Encode normals in the mesh "Bake" from high-poly mesh Introduced 1996, Dreamcast (1998) first console with hardware support



Normal Mapping Examples

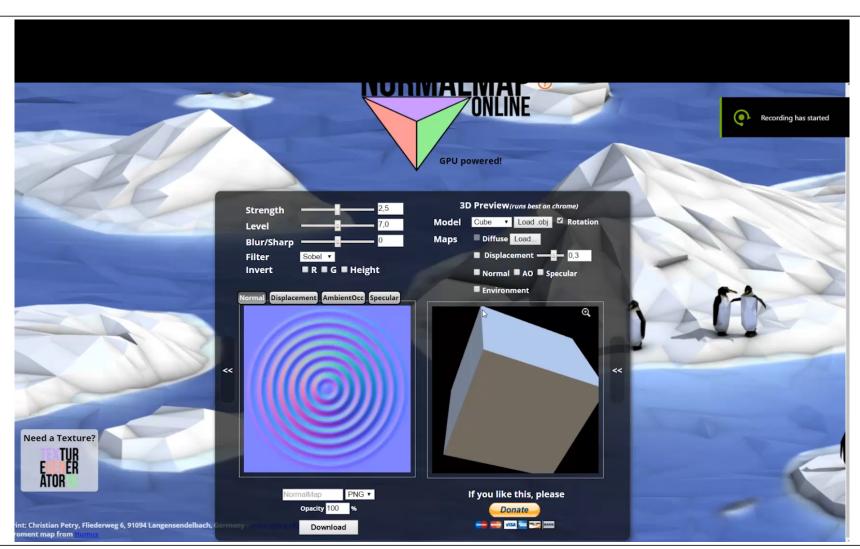




Doom 3, 2004

Normal Mapping Examples





Normal Maps



Use a normal texture to encode the map

normal = 2 * color - 1;

Default color is blueish

- **1** (128, 128, 255)
- Geometric interpretation: Perpendicular to the x-y-plane



Tangent Space Normal Maps

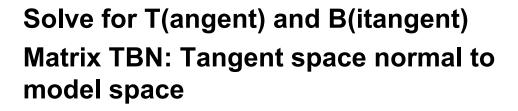


Defines coordinate systems orthogonal to the surface

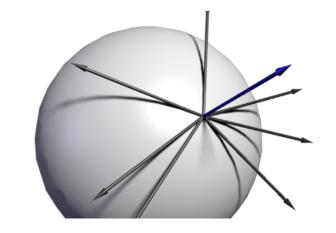
→ Infinite number of systems possible

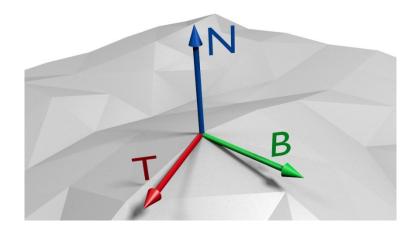
Reuse texture coordinates

- deltaPos1 = deltaU1 * T + deltaV1 * B
- deltaPos2 = deltaU2 * T + deltaV2 * B



$$\begin{pmatrix} T & B & N \\ T & B & N \\ T & B & N \end{pmatrix}$$

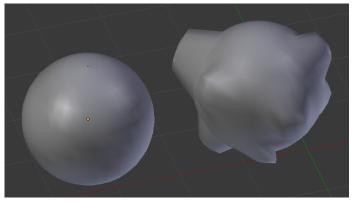




Object-Space Normal vs. Tangent-Space Normal Map



Low and high-poly mesh



Tangent space normals



Object space normals

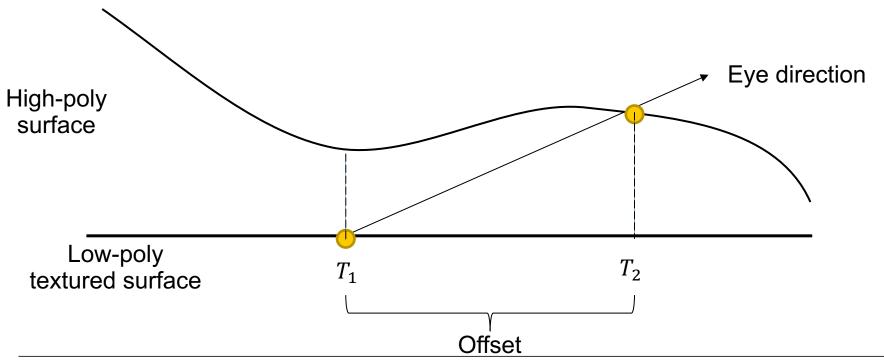


Parallax



We should see the texture at T2, but we see the texture sampled at T1

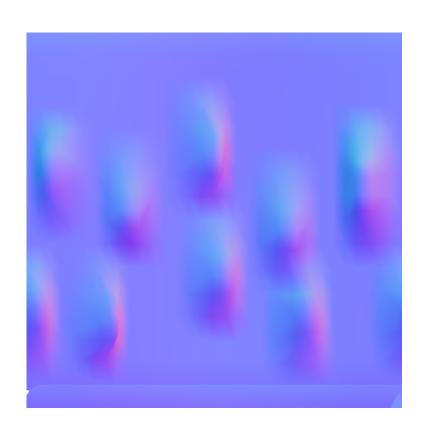
→ Goal: find the correct offset to sample the texture at the correct position



Parallax mapping (2001)



Additional input: Heightmap with values between 0 and 1



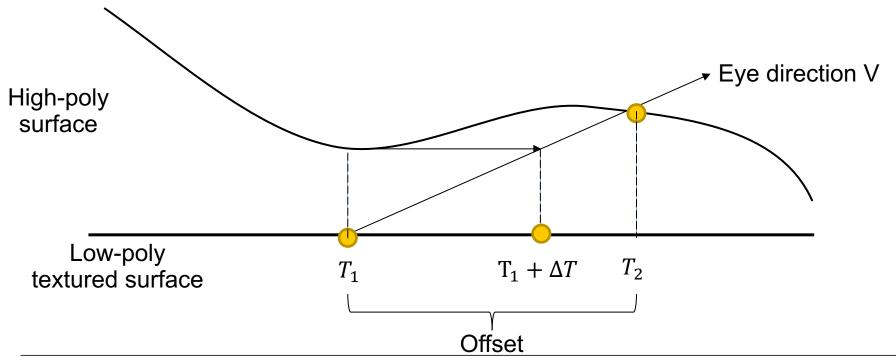


Parallax mapping (2001)



Approximation

- Get the height at T1
- Ray trace from this point parallel to the surface until it intersects view vector
- Use the length as the offset's approximation



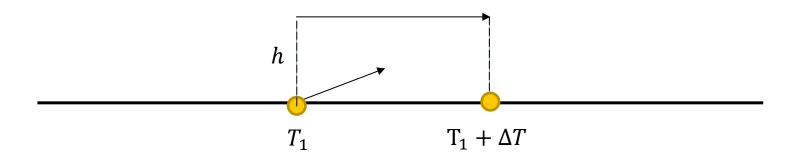
Calculation



Bring view vector into tangent space

Normalize
$$\Rightarrow$$
 V = $\begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix}$ where V_{x,y} = $\begin{pmatrix} V_x \\ V_y \end{pmatrix}$ is a 2D vector in the plane and V_z points upwards

$$\Delta T = \frac{V_{x,y} \cdot h}{V_z}$$



Parallax Mapping Example



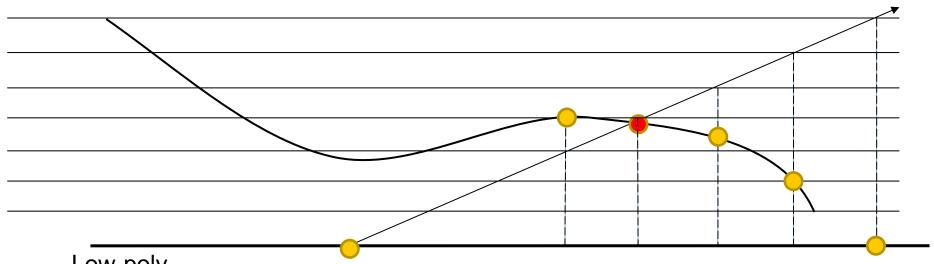


Steep Parallax Mapping (2005)



Improve the calculation by repeating it

Divide the heightmap into layers and test for each layer



Low-poly textured surface

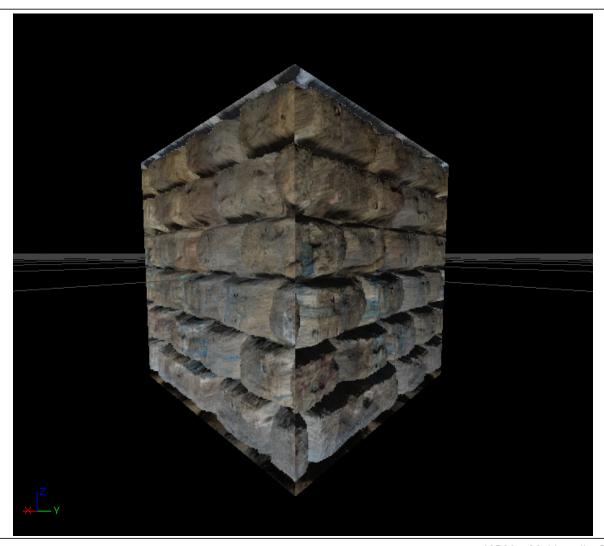
Steep Parallax Mapping Example





Parallax Occlusion Mapping (2006)





Parallax Occlusion Mapping



Use the last steps of Steep Parallax Mapping Interpolate the result based on the relative height differences

Displacement Mapping



Bump/normal mapping add the illusion of depth during shading

Displacement actually changes the geometry by moving vertices

Really useful if GPU supports it

Goes well together will tesselation

 Add vertices where surface detail is needed



ORIGINAL MESH



DISPLACEMENT MAP



MESH WITH DISPLACEMENT

VR - The death of normal maps?





VR - The death of normal maps?



Normals maps don't supply real height differences

No parallax

User can get close to most surfaces, can test for parallax with head movements

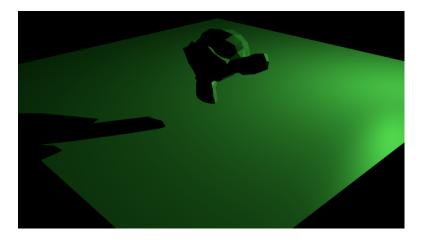
Solutions

- Use displacement or higher resolution meshes for everything that is close
- Use normal maps for fine details and relatively far-away surfaces
- Use parallax mapping

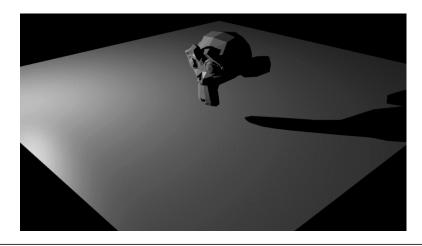
Forward Shading





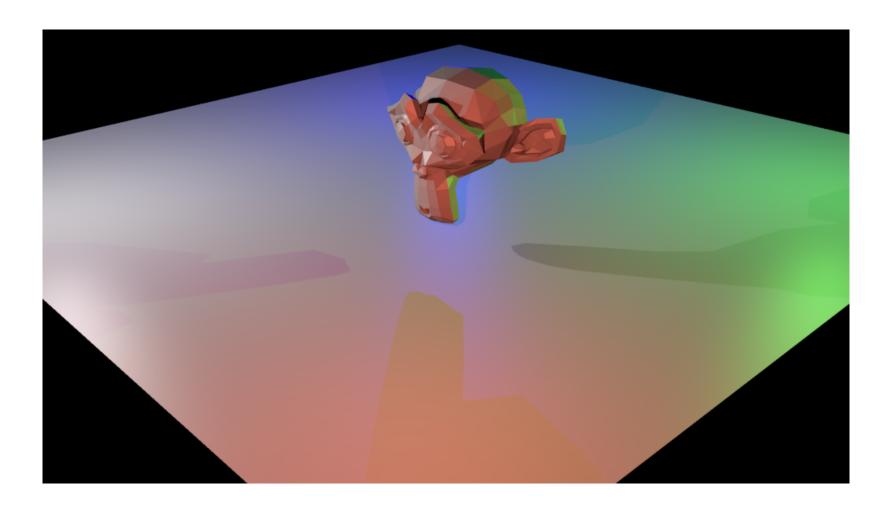






Forward Shading





Forward Shading



a.k.a. what we have been doing so far

For each light source, render each object

- A certain number of lights can be batched into one pass, but still the shader will run several times
- Might use the closest x lights, but that changes the result

Blend/add together the influences in the frame buffer

If we have thousands of lights, we kill performance



Render the whole geometry into a (set of) buffer(s) (G-buffer), including

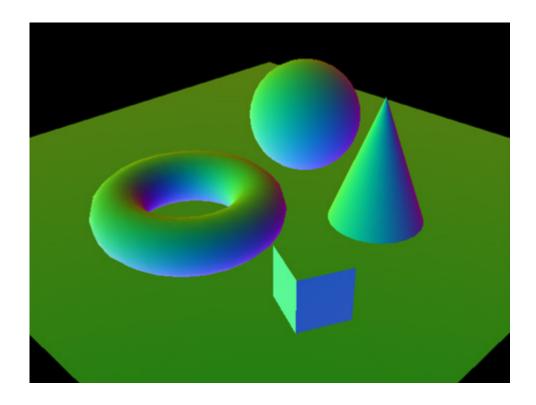
- Normals
- Colors
- Texture coordinates

Calculate the shading, for each pixel once and only for the lights that influence the pixel

→ Main difference to forward rendering No need to render everything for each new light

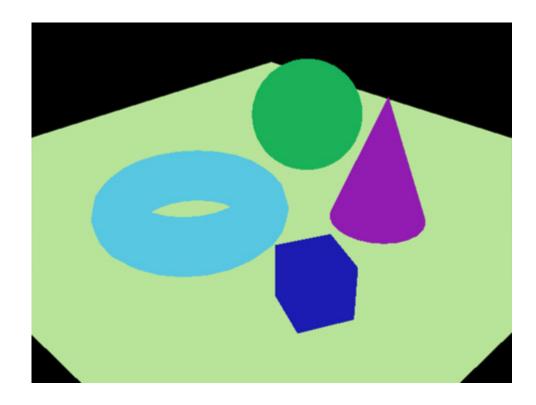


Buffer for normals



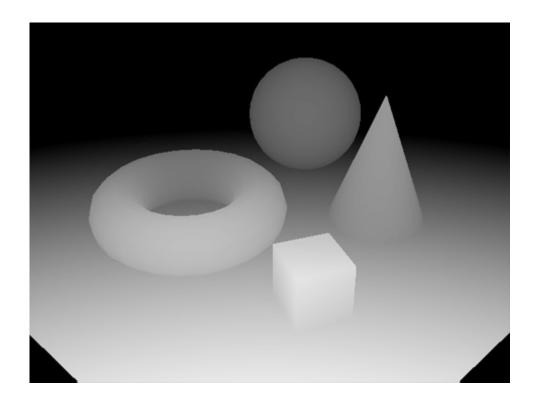


Buffer for different objects



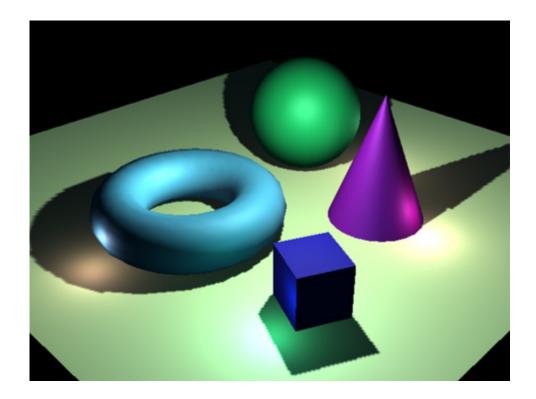


Depth Buffer





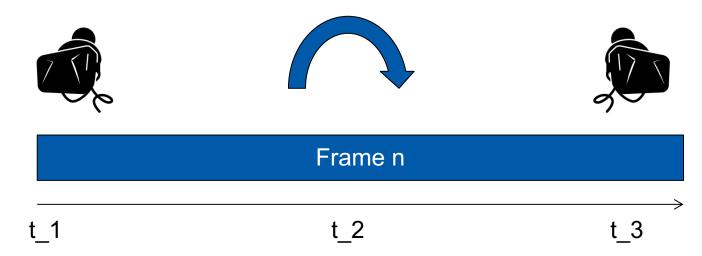
Carry out lighting calculations on the buffers Each geometry rendered once Area of light effects for point/spotlights limited



Virtual Reality Frame Time



Which head position to use?

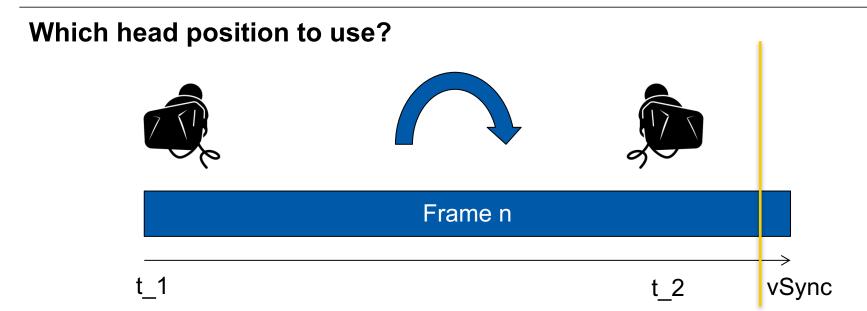


Future positions often predicted by HMD

- E.g. using the measured acceleration, physiological models
- Can use timewarp mechanism → will look at this in a later lecture

VR Frame Time: Time Warp





t1: Render image including depth buffer

t2: Update head position, reproject image

Time warp



Render to texture

Project back from 2D to 3D

Apply new camera rotation (ideally only rotation)

Re-project to 3D

"Pulling in black"

- We only have a 2D image as the reference
- Pixels that are occluded are not in the image "shadowed"
- If we move too fast or don't use pure rotation: We have nothing to interpolate with
 - Display black
 - Display blend of nearby colors
 - ...

Time warp explanation





https://www.youtube.com/watch?v=WvtEXMIQQtI

Animations





Animating whole objects – MVP matrix



projection * view * model

Animate the model matrix to animate an object
Animate the view matrix to change the camera's viewpoint
Animate the projection matrix for FOV changes (scopes, binoculars)

Be careful about the order

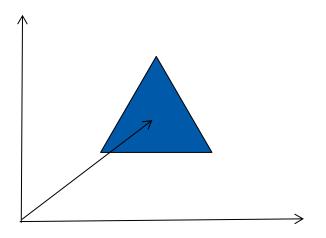
→ Can be reversed depending on matrix layout

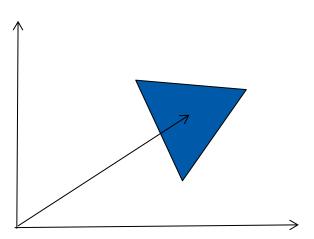
Rotation Off-Center



model = (translate to end position) * rotation * (translate rotation center to 0)

Needed when the object is to be moved off-center (pivot point not at the model's origin)





Scale





Super Mario 64, 2004

Shear

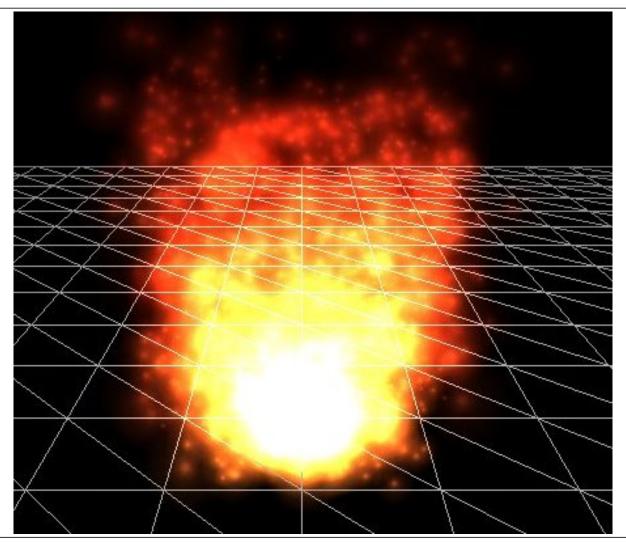




Motor Toon Grand Prix, 1994

Particle Systems (more in 2 lectures)





Fluids

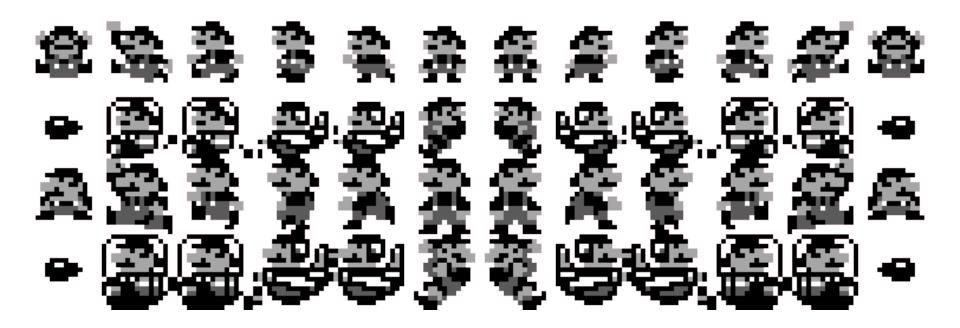




PixelJunk Shooter 2, 2011

Characters - Sprite Sheets





Vertex Animations





Quake, 1996

Vertex Animations



100 frames * 100000 vertices = lots of data

Blend Vertex Positions



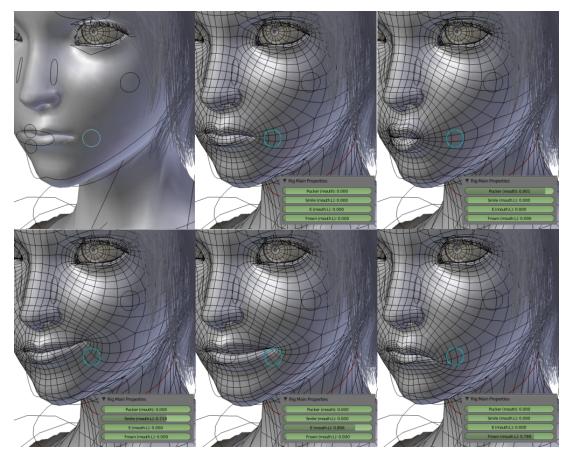


Dragon Quest 8, 2004

Faces

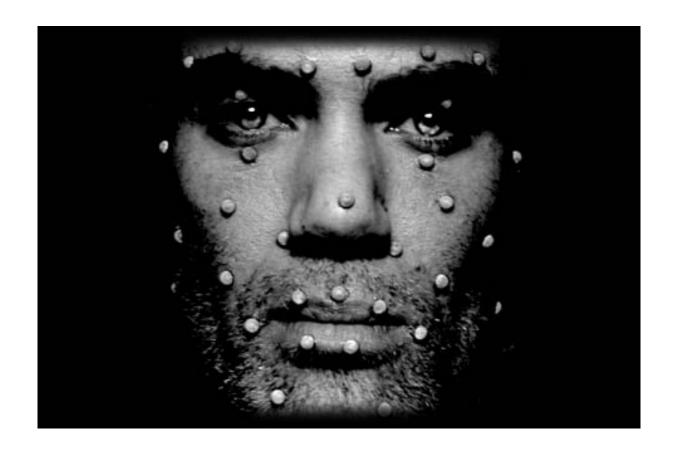


Morph target animation



Performance Capture





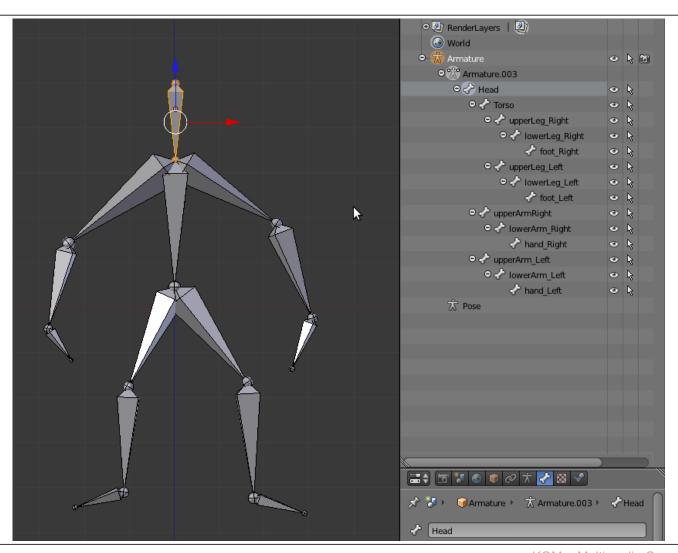














One bone – One Transformation matrix

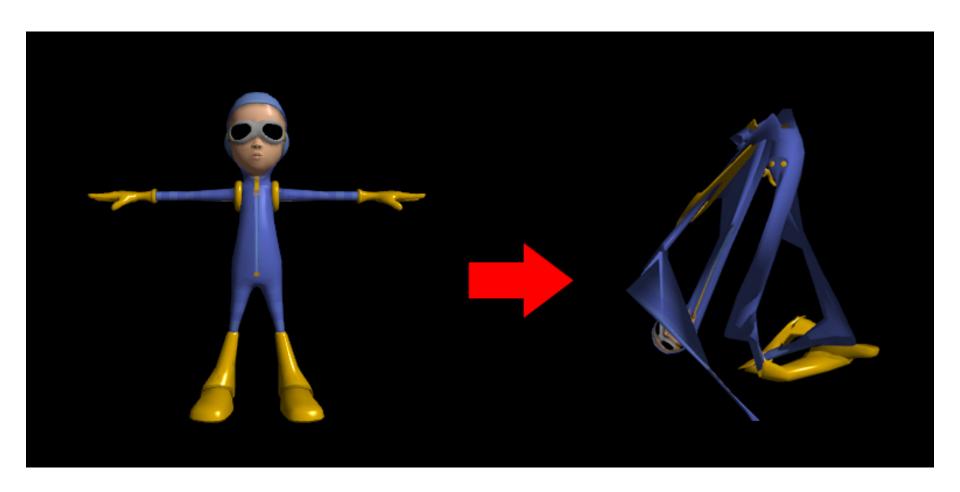
- Or just a rotation
 - Depends on your gfx tool

Animation

- Just an array of small transformation matrix arrays
- Framerate can be low
 - Interpolation works fine

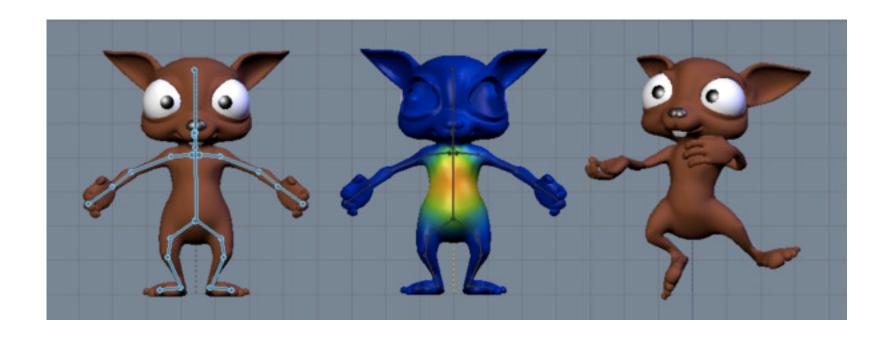
Skinning (gone wrong)





Skinning





Skinning



For each vertex

Array of (weight, index)

At start

Compute inverse of every bone transform matrix (multiply all along the way to the bone) → goes from model space to bone space

For each animation step

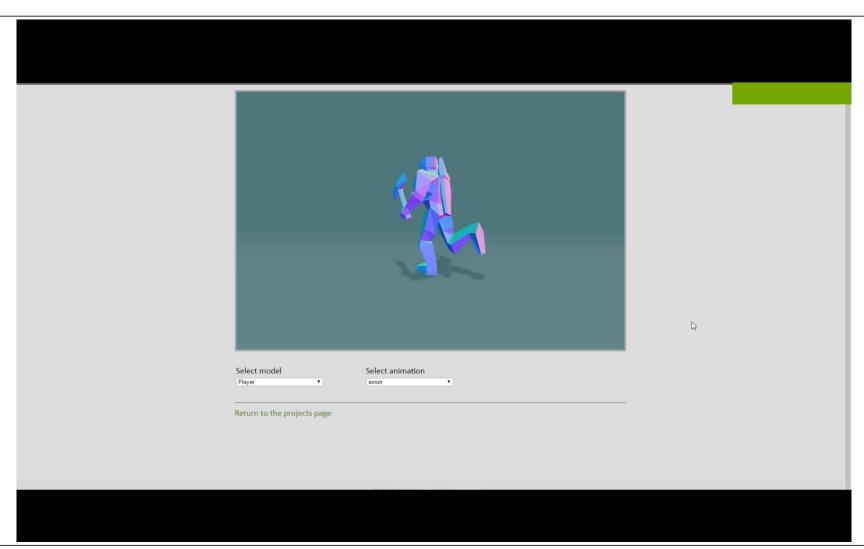
- Compute new transform matrices
- For each bone compute new transform * inverse

For each vertex

- For each weight (usually <=4 or 8)
 - Compute (new transform * inverse * vertex) * weight
- Sum it up

Quiz: Which animation?





Quiz: Which animation?

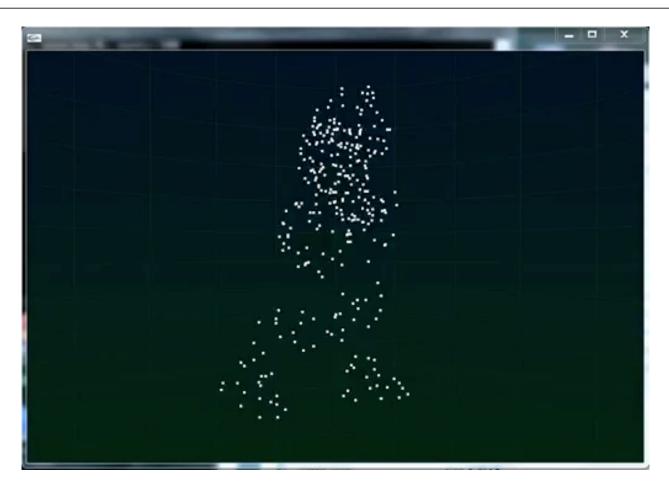




https://www.youtube.com/watch?v=J8JPVj-AYTw

Quiz: Which animation?





https://www.youtube.com/watch?v=AxEdZiQISOA

Motion



Root Motion: Save motion of root bone during animation

- Motion is "hard-coded"
- Can be fine-tuned by the designers, e.g. different speeds at different points

No root motion: Character stays in one place

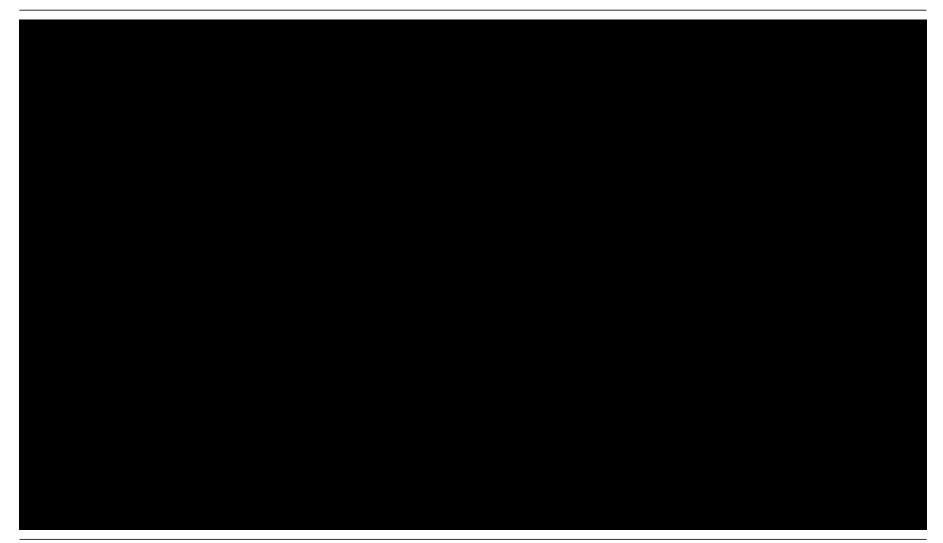
- + Exact control (for animators)
- Somewhat less control for gamers
- More animations needed

- + Can be blended easier
- + Can be used more versatile
- Footskating
- Accelerations

- ...

Root Motion Example





Motion Capturing





Motion Retargeting





https://www.youtube.com/watch?v=Vn-vVzMGgec

Inverse Kinematics



Forward Kinematics

Input: Bone rotations

Output: Final positions

Inverse Kinematics

Input: Final positions

Output: Bone rotations

Inverse Kinematics





Super Mario Sunshine, 2002

Inverse Kinematics



Numerical, iterative solution using Jacobi Matrix

See Robotics Lectures



Unexpected Deformations



"Achselhölle", Candy Wrapper Problem

Skinning with Dual Quaternions

L. Kavan, S. Collins, J. Zara, C. O'Sullivan

Trinity College Dublin Czech Technical University in Prague

Spherical Skinning

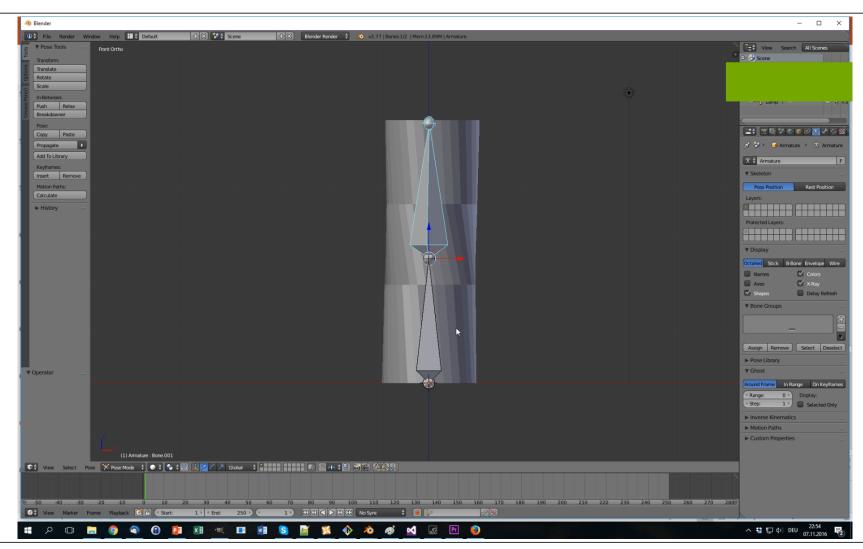
http://www.crytek.com/download/izfrey_siggraph2011.pdf

Dual Quaternion Skinning

https://www.youtube.com/watch?v=4e_ToPH-I5o

"Achselhölle" visualized





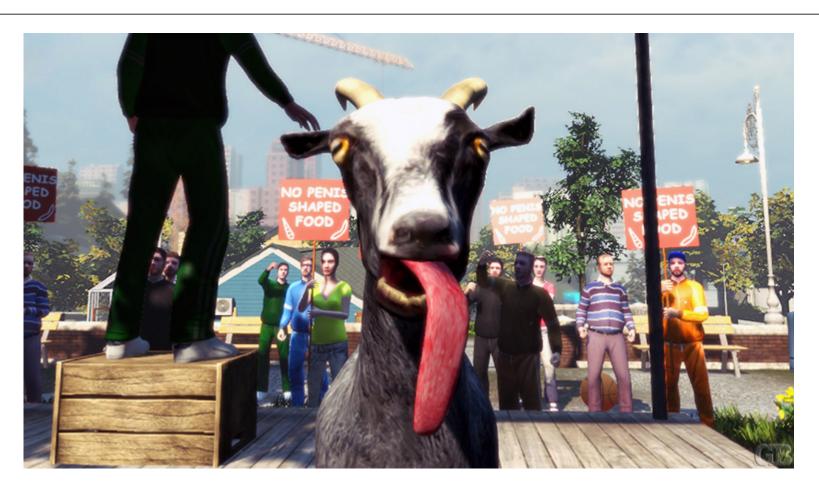
Muscles





Physical Animations





Goat Simulator, 2014

Hair, Cloth,...

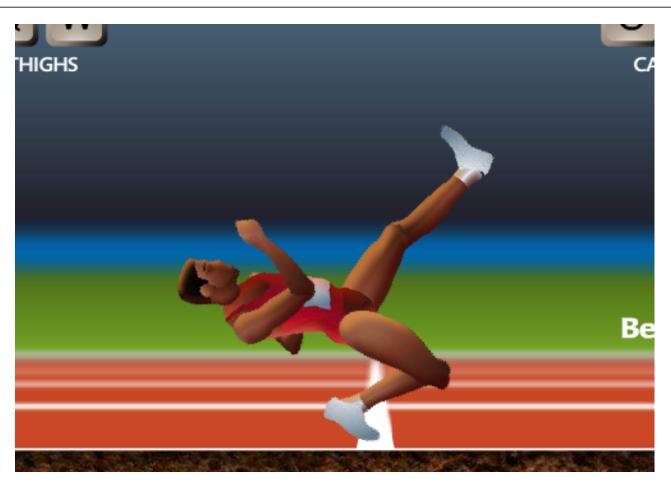




Tomb Raider, 2013

Rag Dolls





QWOP (2008)

Mixture between forwards and physically based



During regular animation

→ Driven by forward animation

Physical Interactions

- On becoming unconscious
- On stumbling
- → Switch to ragdoll behavior

On regaining control

→ Blend to the forward kinematics again

Summary



Normal maps, bump mapping

- Increase the visual quality without increasing vertex count
- Bake from higher-poly version or paint/generate

Displacement maps

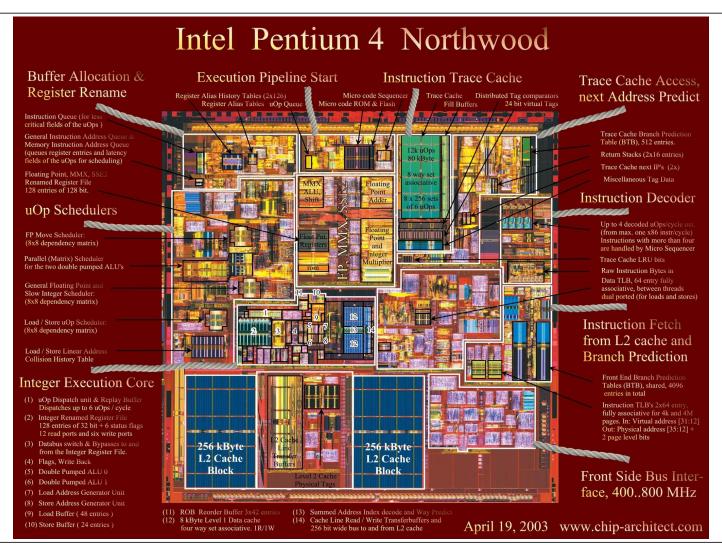
- Increase visual quality by increasing vertex count
 - But our badass GPU does it for us

Animation techniques

- Morph Targets
- Skeletal animation

CPU internals

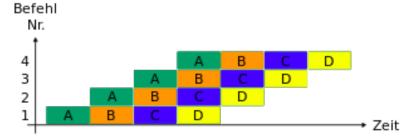




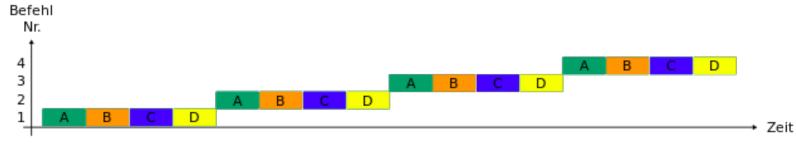
Pipelining



Befehlsverarbeitung mit Pipelining



Befehlsverarbeitung ohne Pipelining

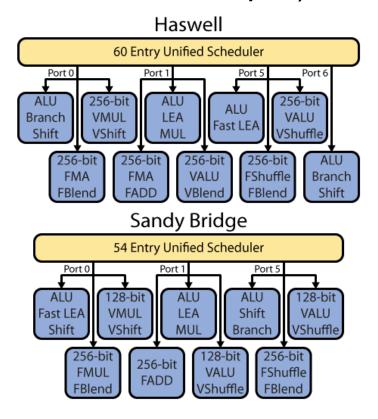


https://de.wikipedia.org/wiki/Pipeline_(Prozessor)

Multiple Execution Units



 " Note that Figure 3 does not show every execution unit, due to space limitations." (from http://www.realworldtech.com/haswell-cpu/4/)



Hazards



Structural Hazards

Out of hardware

Data Hazards

Data dependencies

Control Hazards

Dynamic branching

Structural Hazards



Example

- One command is in the fetch state and wants to read memory
- One command wants to write to the memory

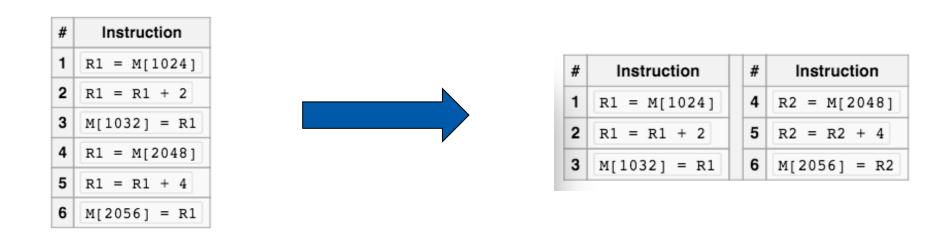
Modern CPUs add more ALUs

Already at a very high level

Data Hazards



Sometimes just register uses, but not real data dependencies



→ Register renaming

CPU uses more registers internally than can be directly addressed

Data Hazards



Compiler can help

- Reorder instructions
- Depends highly on CPU

Out-of-Order CPUs

- Can reorder instructions themselves
- Can incorporate current situation in decisions
- All current x86 CPUs are out-of-order
- More and more ARM CPUs are out-of-order
- PS360 are in-order
- Current generation consoles are out-of-order

Control Hazards



Speculative execution

Branch Prediction more and more sophisticated

Branch prediction example



```
int main()
   // generate data
   const unsigned arraySize = 32768;
   int data[arraySize];
   for (unsigned c = 0; c < arraySize; ++c)
        data[c] = std::rand() % 256;
   // !!! with this, the next loop runs faster
   std::sort(data, data + arraySize);
    // test
   clock t start = clock();
   long long sum = 0;
   for (unsigned i = 0; i < 100000; ++i)
        // primary loop
        for (unsigned c = 0; c < arraySize; ++c)
            if (data[c] >= 128)
                sum += data[c];
   double elapsedTime = static_cast<double>(clock() - start) / CLOCKS_PER_SEC;
   std::cout << elapsedTime << std::endl;</pre>
    std::cout << "sum = " << sum << std::endl;</pre>
```

Memory Access



Cache Hierarchy critical for performance

L1 cache ~ KiloBytes

L2 cache ~ MegaBytes

Main memory ~ GigaBytes

L1 cache ~ 0.5 ns

L2 cache ~ 7 ns

Main memory ~ 100 ns

More information

Scott Meyers - CPU Caches and Why You care

https://vimeo.com/97337258

http://gameprogrammingpatterns.com/ data-locality.html

Memory Access



Access pattern prediction

Works best when data is reused or for sequential data reads

Cache Lines

- Memory read in blocks
- ~ 64 Bytes
- Proper data alignment can help

POD



```
"Plain old data"
struct Data {
  int a;
  float b;
};
```

Predictable data structures

No constructor calls during array allocation

No additional data for virtual function pointers

Data data[64]; Linear data of 64*sizeof(Data) bytes

Memory alignment



Add unused data

Use system specific things

```
posix_memalign(..)
```

Use alignas in C++ 11

```
struct alignas(16) Data {
  int a;
  float b;
};
```

alignas(128) char cacheline[128];

Packed structures



```
struct InsufficientParticle
                                //total size 44 bytes
 bool visible;
                                //31 bits of padding
 Texture* texture;
                                //pointer to texture
 int alpha;
                                //only needs 0 to 256
                                //enumeration – 4 possible types
 int type;
 Vec3 position;
 Vec3 velocity;
```

Steve Rabin: Game Programming Gems 8: Game Optimization through the Lens of Memory of Data Access

Packed structures



```
//total size 30 bytes
struct Efficient particle
 Vec3 position;
 Vec3 velocity;
 unsigned char alpha;
                               //saved 3 bytes (0-255)
 unsigned char rotation;
                               //saved 3 bytes (0-255 degrees)
 unsigned texture:4;
                               //saved 28 bits (texture index)
 unsigned type:2;
                               //saved 29 bits (enumeration)
 unsigned visible:1;
                               //saved 31 bits(single bit)
```

Cache efficiency



Order from largest to smallest members to reduce padding

sizeof(MyStruct) gives you the size including padding

Separate hot and cold data

- Keep hot data (often used) close together
- Watch out for gaps between hot data

Prefetch data

- Available on some platforms
- Make sure data is available on time

Lock the cache

Some platforms, e.g. Wii, allow parts of the cache to be locked and managed by the application

Summary



CPU Internals

Hazards

- Structural Hazards
- Data Hazards
- Control Hazards

Memory access

Memory alignment

Evaluation of Redirected Walking Methods in Virtual Reality



Dauer:

■ ~30min

Ort:

■ S3/20 103, Rundeturmstraße 10,

Eintragen hier:

https://doodle.com/poll/trhg73ibtp5a2esn

Das Wichtigste:

Es gibt Kekse für alle Teilnehmer :D

Bei Fragen:

martin.moeller@stud.tu-darmstadt.de

