

# Game Technology

Lecture 1 – 17.10.2017  
Input and Output



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Dipl. Inform. Robert Konrad  
Polona Caserman, M.Sc.

Prof. Dr.-Ing. Ralf Steinmetz  
KOM - Multimedia Communications Lab

# Hi



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## Dr. Stefan Göbel

- The boss



## Robert Konrad

- Lecturer 1



## Polona Caserman

- Lecturer 2



## Dr. Florian Mehm

- Ex-Boss



# Organization

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## Lecture (V2)

- Lecturers: Robert Konrad, Polona Caserman

## Exercise (Ü2)

- Theory and implementation (game engine programming)

## Language

- Answers are accepted in German and English (exercises and exam)

# Organization

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## Sign up with TuCan

## Current news

- Website@KOM (static information only): <https://www.kom.tu-darmstadt.de/teaching/current-courses/gametech-lecture/overview1/>
- Wiki, including the lecture slides and script:  
[wiki.ktxsoftware.com](http://wiki.ktxsoftware.com)
- Fachschafts-Forum:  
<https://www2.fachschaft.informatik.tu-darmstadt.de/forum/viewforum.php?f=557>
- [game-technology@kom.tu-darmstadt.de](mailto:game-technology@kom.tu-darmstadt.de)

# Exercises

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## Released after each lecture

- First exercise will be a special case, intended to bring everyone up to speed with git repositories, engine, ...

## Exercises will have due dates

- These dates are non-negotiable

## Bonus Points

- >50%: 0.3; >70%: 0.7; >90%: 1.0
- The exam has to be passed without the bonus points – bonus is added only after the exam has been passed regularly
  - The bonus is applied by linearly interpolating
- Your bonus points will be uploaded to your git repository

# Exercises

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## Group Exercises

- Allowed to complete exercises in groups up to **3 members**
- Turn in exercises via git until the noted time

## Group Formation (1-3 people – please form teams!)

- Choose your own name
- Send group information to [game-technology@kom.tu-darmstadt.de](mailto:game-technology@kom.tu-darmstadt.de), including:
  - Group name
  - Names of all members
  - Mail addresses of all members
- **Until Friday, October 20th, 23:59**

## Turning in Solutions

- Theory: Digital, scan written answers or work digitally (PDF, txt, ...)
- Source Code: See C++ lecture part

# Exercises

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## 1 exercise per week

- Due until the next lecture
- No exercises during winter break

## Git

- Instructions are sent with your group login



# Relation to other lecturers

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## Serious Games

- Lecture
- Seminar
- (Projekt)Praktikum

## Urban Health Games

## FIF Schwerpunkt Serious Games

- [http://www.fif.tu-darmstadt.de/fif\\_topics\\_structure/fif\\_serious\\_games\\_structure\\_ref/index.de.jsp](http://www.fif.tu-darmstadt.de/fif_topics_structure/fif_serious_games_structure_ref/index.de.jsp)

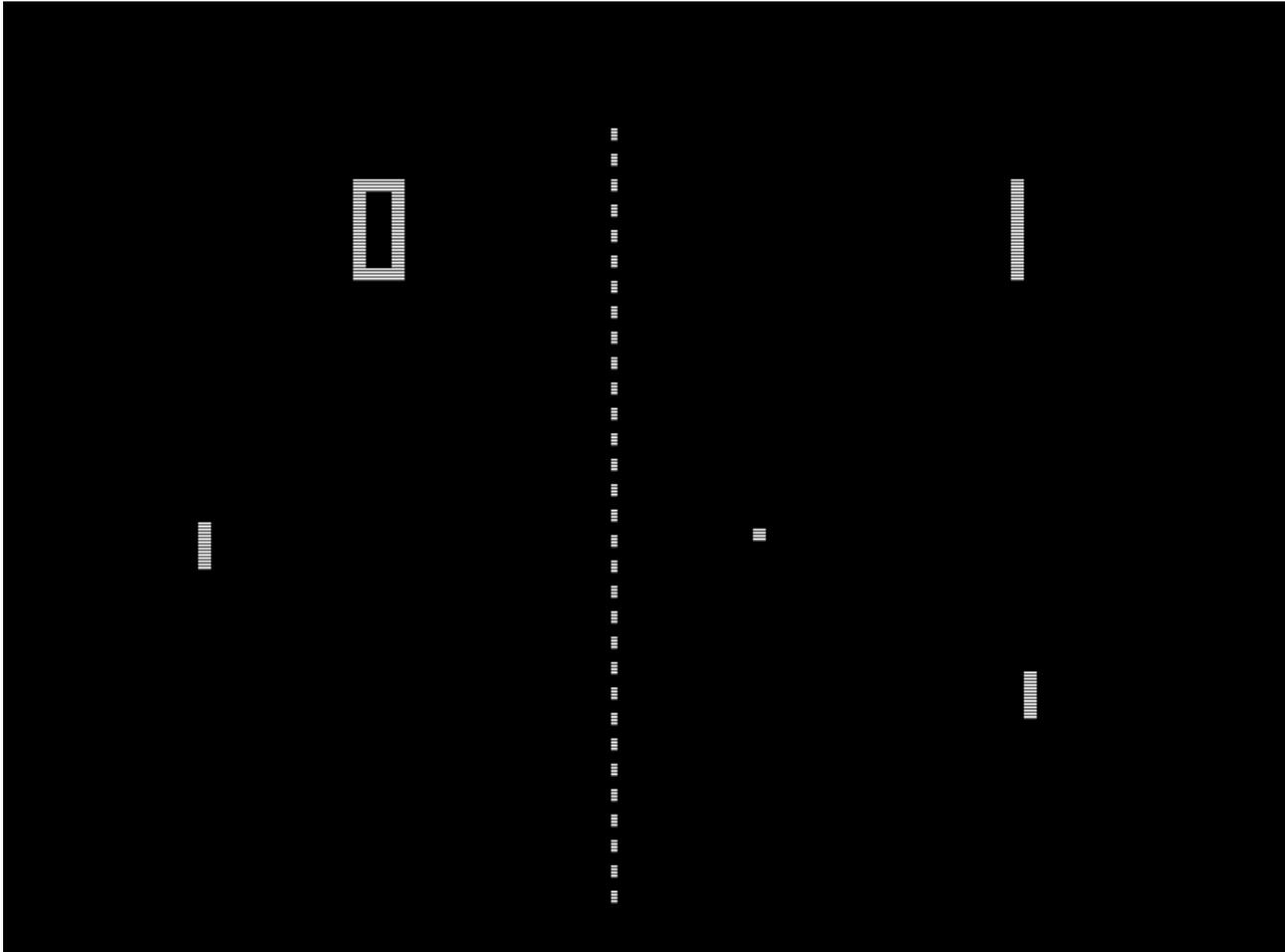


## Computer Graphics

# Video Games



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Pong, 1972

# Focus on Performance

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## Manual memory management

- Pre-loading
- Cache optimization

## Shader Programming

## Separate lecture part for some lectures

- ~1 hour theory
- ~30 minutes programming, technology (e.g. GPU)



# Motivation

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## Shaded Pixels per Second

- 720p @ 30 Hz: 27 million pixels/sec
- 1080p @ 60 Hz: 124 million pixels/sec
- 30" Monitor 2560x1600 @ 60 Hz: 245 million pixels/sec
- VR 1512x1680x2 @ 90 Hz: 457 million pixels/sec
- 4k Monitor 4096x2160 @ 60 Hz: 530 million pixels/sec

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# Pseudo-realistic realtime simulations

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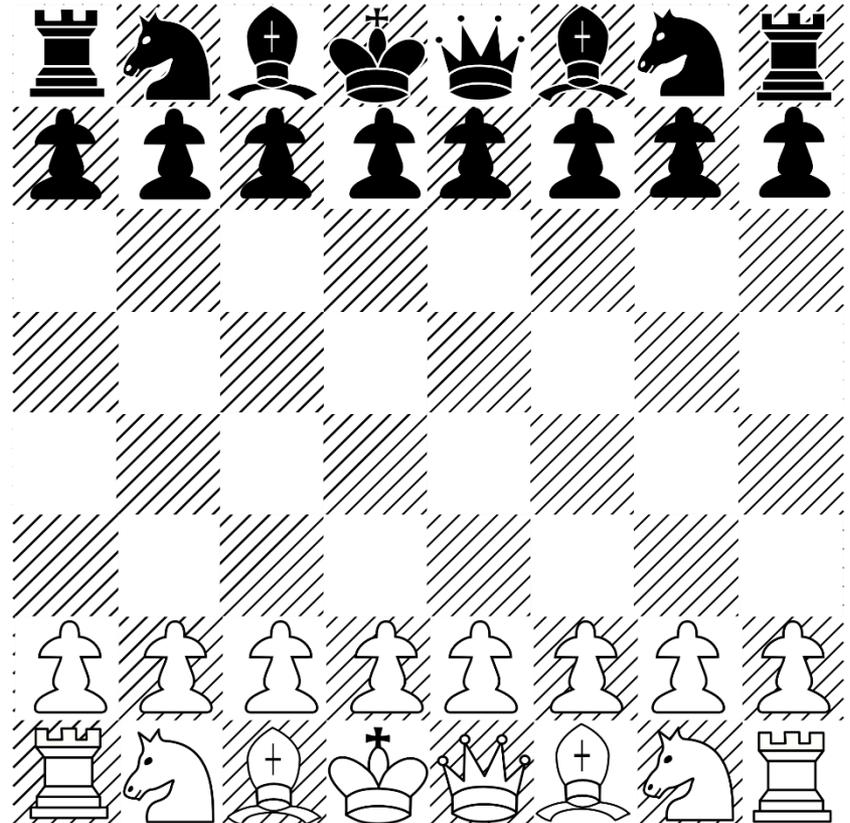


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# Pseudo-realistic realtime simulations

## No chess

- Focus on fast/realtime apps
- Running in a game loop



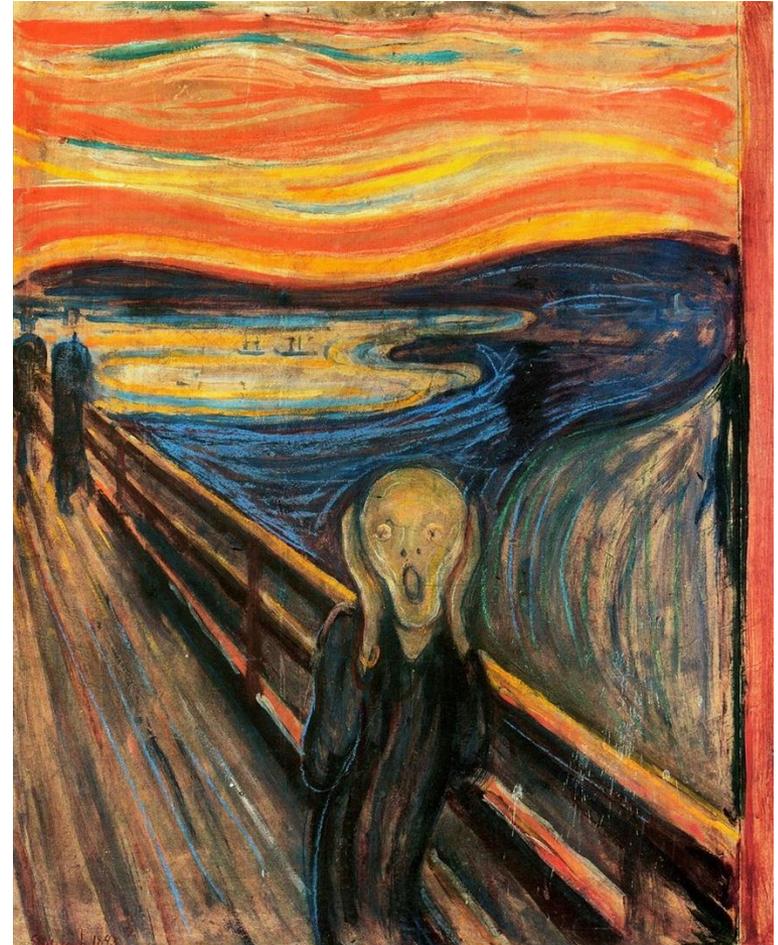
# Pseudo-realistic realtime simulations



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## No „artsy“ games

- But understanding how to make realistic games also helps with non-realistic games



# Pseudo-realistic realtime simulations



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## No flight simulators for Lufthansa

- Actual realism not necessary
  - ...and probably too slow
- Requires knowledge of human perception



# Human-Machine data transfer

## Human

- Output
  - Pushing
  - Talking
  - Moving
- Input
  - Staggering amounts of data

## Machine

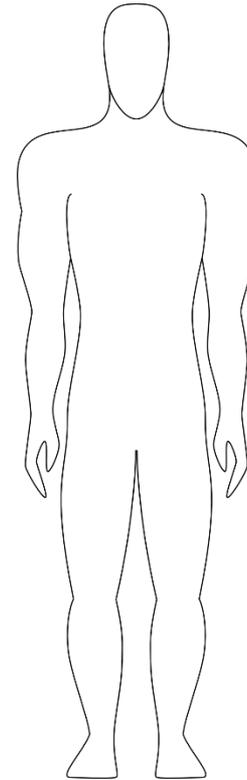
- Output
  - Monitor
  - Speakers
- Input
  - Buttons





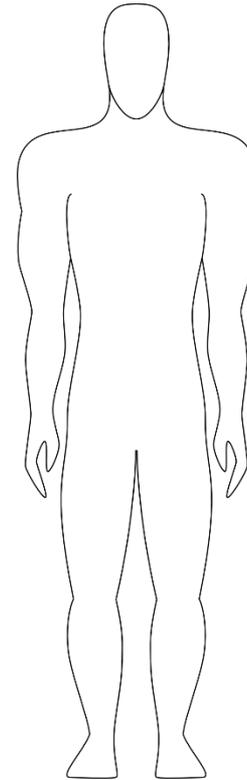
## Five senses

- Sight
- Hearing
- Touch
- Smell
- Taste



## Many senses

- External
  - Sight
  - Hearing
  - Touch
  - Smell
  - Taste
  - Acceleration
  - Temperature
- Internal
  - Kinesthetic
  - Pain
  - ...



# Eyes and Ears



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**Most dominant sensors**

**Measure different kinds of waves**



# Waves

Wave Direction

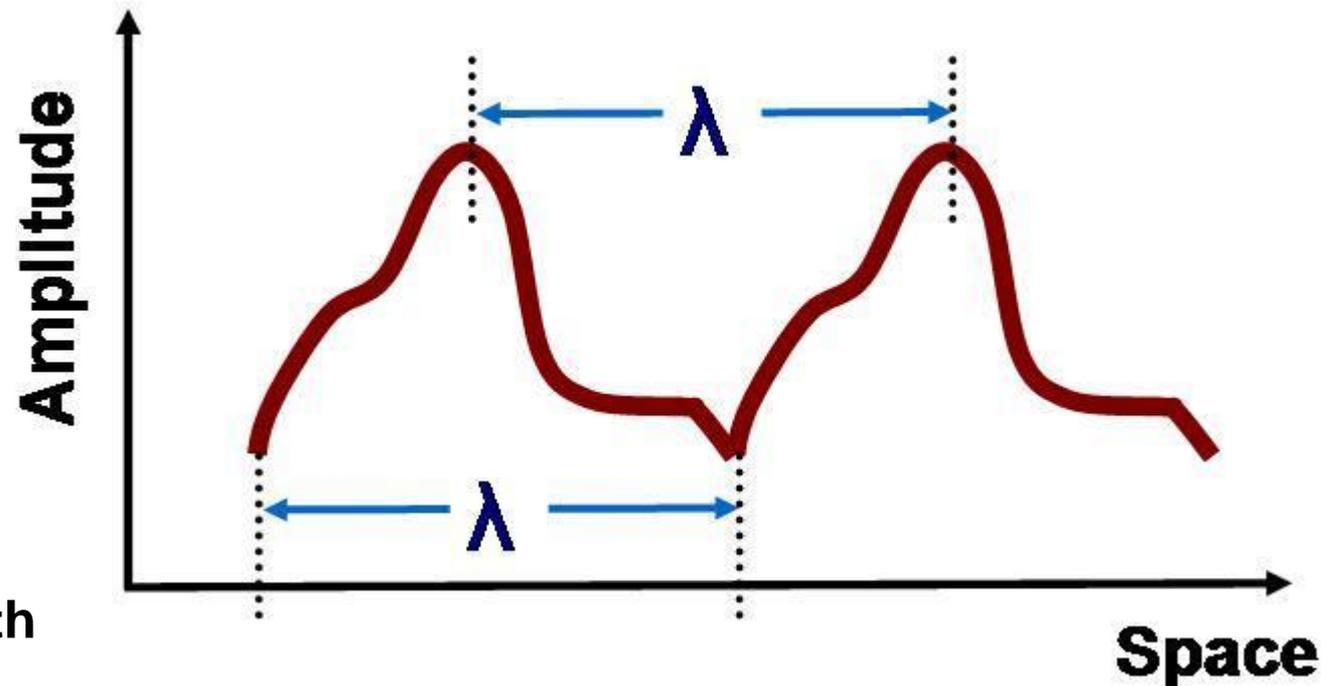
Oscillation Direction (for transverse waves)

Amplitude

Speed (often constant)

Wavelength

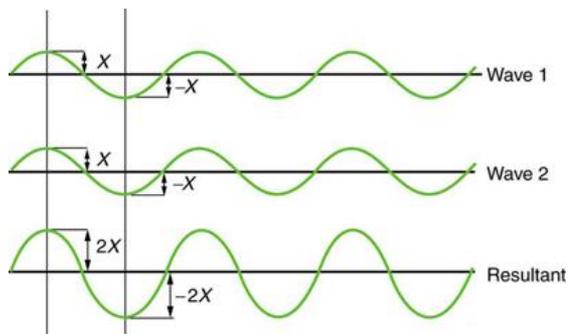
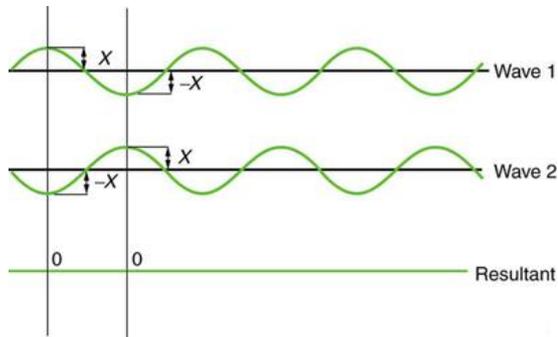
Waveform



Frequency =  
Speed / Wavelength

# Wave Interaction

## Superposition



# Light Waves

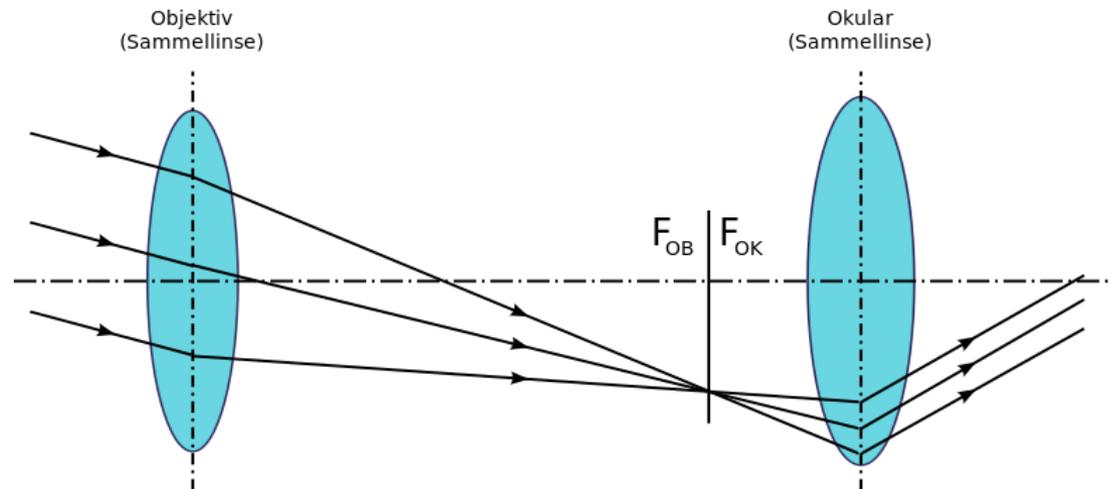
## Electromagnetic waves

## Transverse waves

- Direction of oscillation orthogonal to wave direction

## Very fast

## Usually discussed using simplified models



# Optical Sensors

## Two units

- Surround view or 3D view depending on arrangement



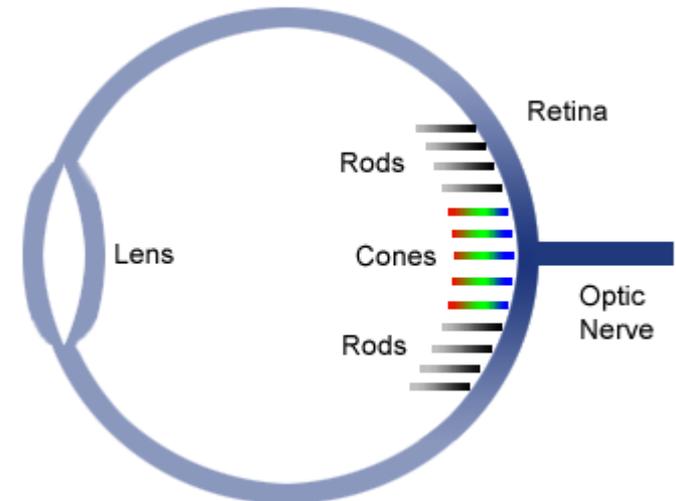
# The eye

The lens focuses light on the retina

Rods measure light intensity/energy  
(wave amplitude and frequency)

Cones only react to specific wavelengths

- Three different kinds
  - Red,
  - green, and
  - blue



# What do you see?

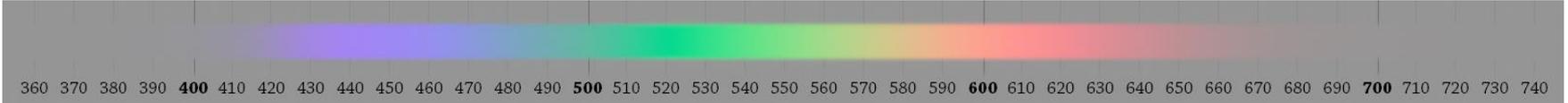
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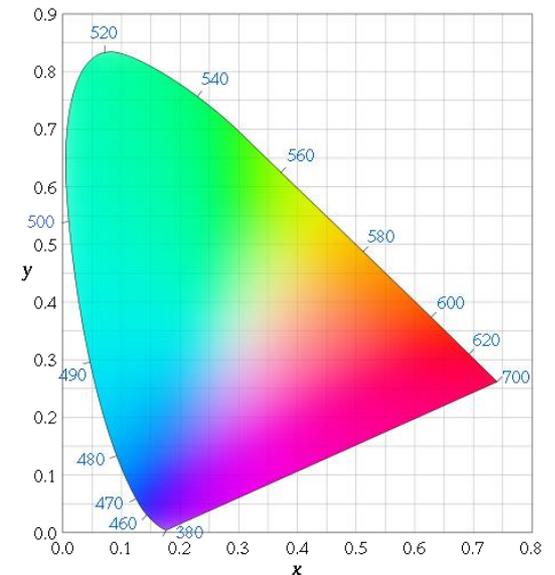
# Red, green and blue



## Brain interpolates colors

## Brain sees magenta when interpolation fails

- Same amounts of blue and red but no green
- See <http://richannel.org/colour-mixing-and-the-mystery-of-magenta>





# Visual Field of Humans

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**Horizontally: ~180°**

**Vertically: ~135°**

**But, the vision quality is not the same across the visual field**

- Binocular vision: ~135°
  - Remaining visual field only visible by one eye
- Color vision
  - Cones mostly in the center of the field of view → good color vision
  - Rods mostly on the periphery → good shape perception

## **Foveated rendering**

- Track what the eyes are focusing
- Reduce detail in the periphery → speed up

# Stereo Vision, Depth Perception

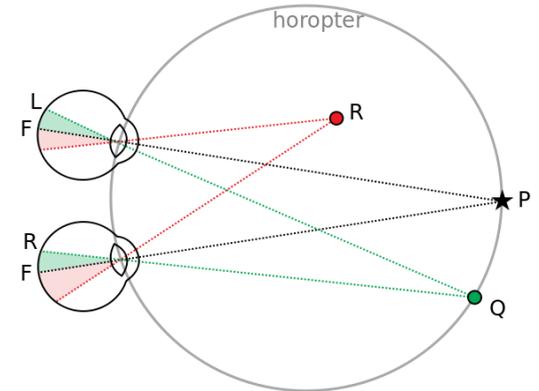
## Distance between eyes

- Interpupillary Distance
- ~6.5 cm in humans

## Monocular cues

## Binocular cues

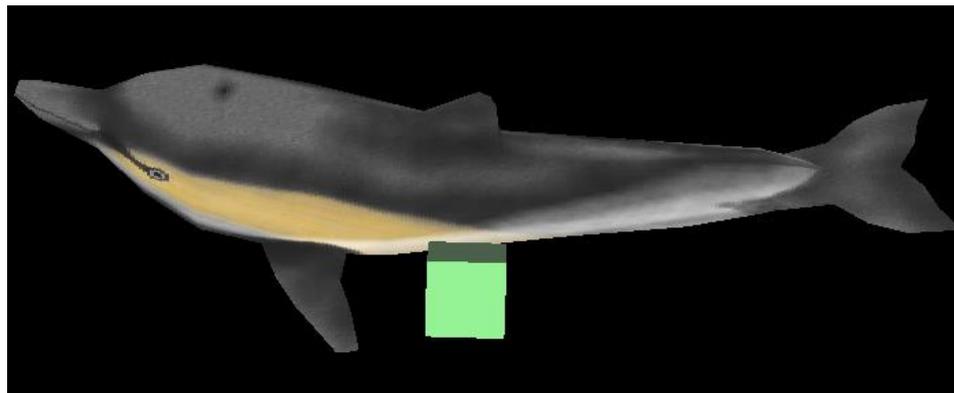
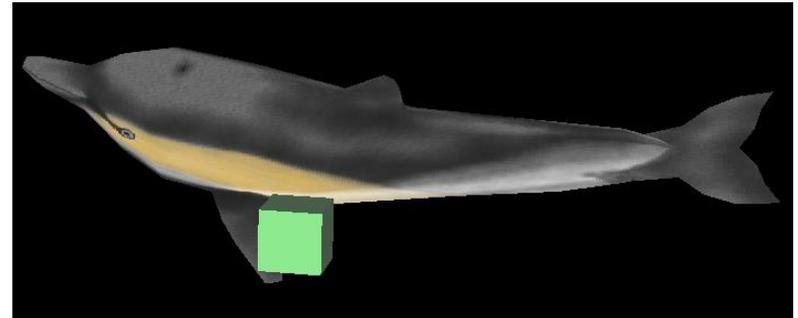
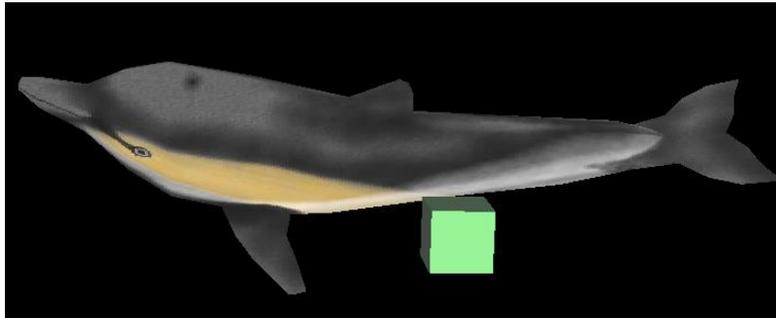
- Stereopsis: Triangulation using difference in both eyes (effective for < 200 m, differs according to sources)
  - Convergence: Using muscles in the eyes (effective for < 10 m)
  - Shadow Stereopsis
- Limits to distances, opens doors for optimization in VR



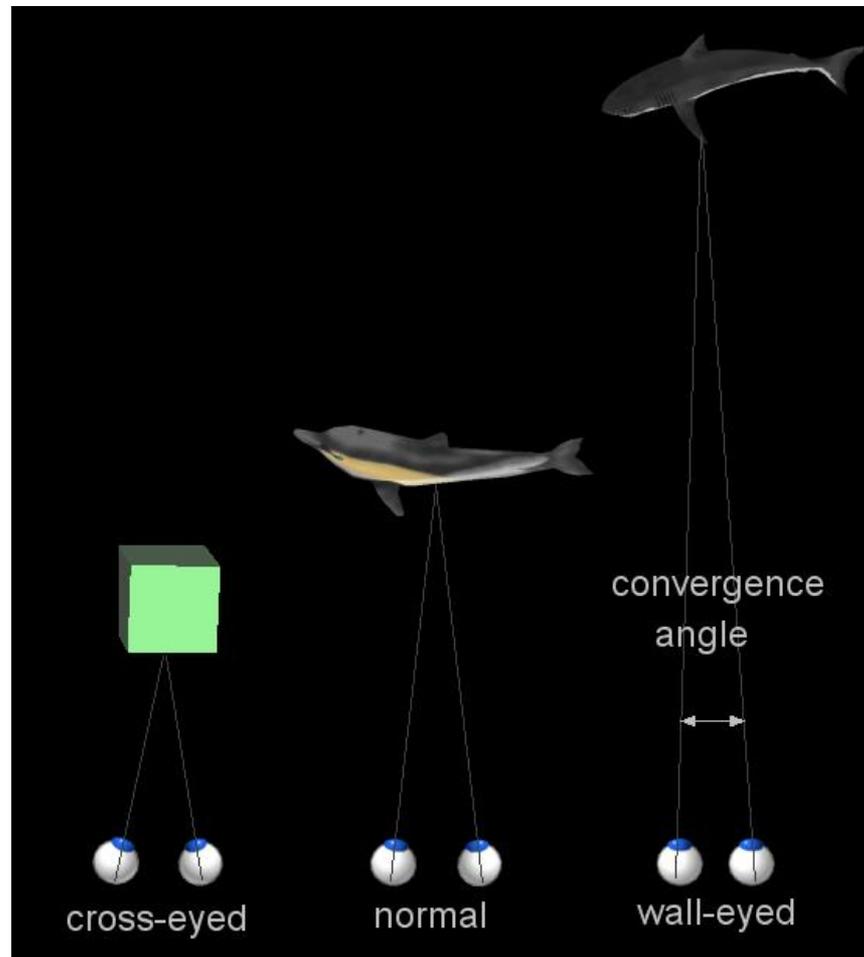
# Stereopsis



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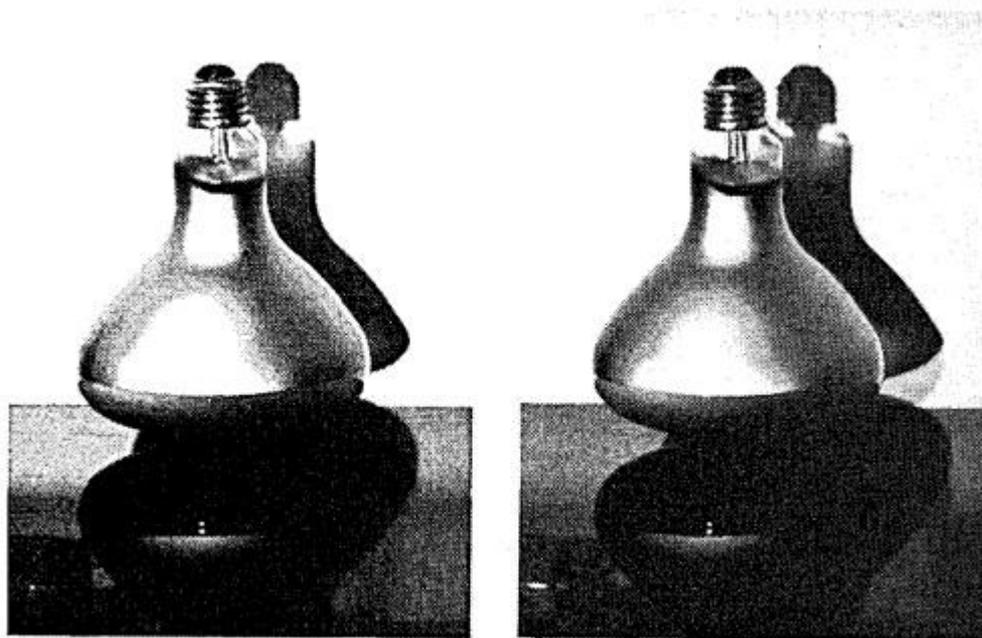
# Convergence



# Shadow Stereopsis

**Antonio Medina Puerta, "The power of shadows: shadow stereopsis,"  
J. Opt. Soc. Am. A 6, 309-311 (1989)**

**Images with no parallax disparities but shadow differences still  
appear to have depth**



# Stereo Vision, Depth Perception



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## Monocular Cues

- Motion parallax
- Depth from motion
- Kinetic depth effect
- Perspective
- Relative size
- Familiar size
- Absolute size
- Accommodation
- Occlusion
- Curvilinear perspective
- Texture gradient
- Lighting and shading
- Defocus blur
- Elevation

# Stereo Vision, Depth Perception



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## Monocular Cues

- **Motion parallax**
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# Motion Parallax



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**Objects at different distances appear to move at different speeds when moving relative to the observer**



Ninja Gaiden II, 1990

# What is missing?



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# Stereo Vision, Depth Perception



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## Monocular Cues

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- Curvilinear perspective
- Texture gradient
- **Lighting and shading**
- Defocus blur
- Elevation
- Aerial Perspective

# Lighting and Shading



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# Stereo Vision, Depth Perception



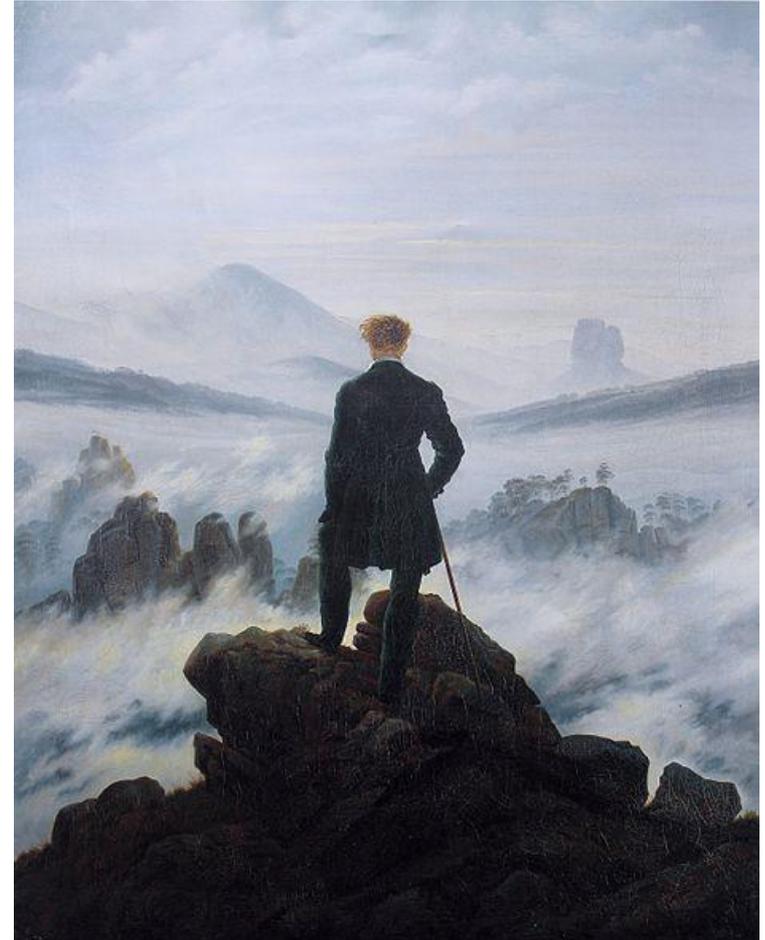
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## Monocular Cues

- **Motion parallax**
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- Relative size
- Familiar size
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- Occlusion
- Curvilinear perspective
- Texture gradient
- **Lighting and shading**
- Defocus blur
- Elevation
- **Aerial Perspective**

# Aerial Perspective

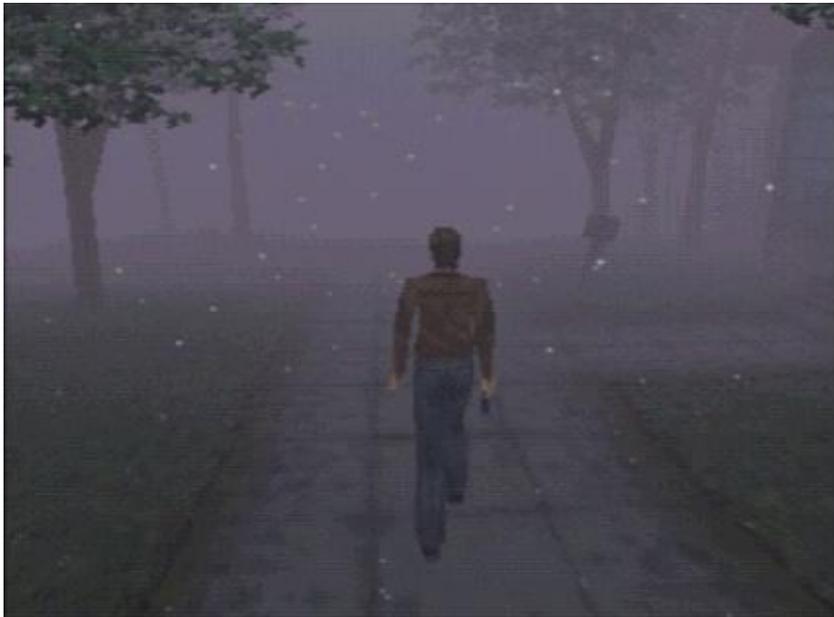
**Due to the influence of the atmosphere, objects far away appear subdued and look more and more like the horizon**



Der Wanderer über dem Nebelmeer, Caspar David Friedrich, 1818

# Aerial Perspective

Used formerly as performance optimization



Silent Hill, 1999

Nowadays, more artistic choice



Firewatch, 2016

# Stereo Vision, Depth Perception



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## Monocular Cues

- **Motion parallax**
- Depth from motion
- Kinetic depth effect
- Perspective
- Relative size
- Familiar size
- Absolute size
- Accommodation
- Occlusion
- Curvilinear perspective
- **Texture gradient**
- **Lighting and shading**
- Defocus blur
- Elevation
- **Aerial Perspective**

# Texture Gradient



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Regular patterns get more densely packed the further they are away



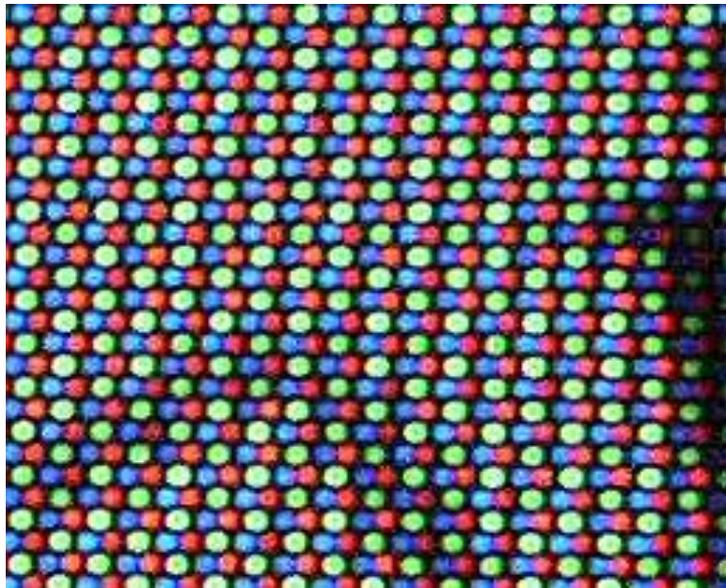
# Monitors



**Exact counterpart to human eye**

**Red, green and blue emitters**

**No physically accurate picture reproduction**



# Computer → Monitor



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## Designated memory area which is transferred to the monitor

- The framebuffer

## Structurally equivalent to the pixel structure

- 1 red byte
- 1 green byte
- 1 blue byte, ...

# Gamma

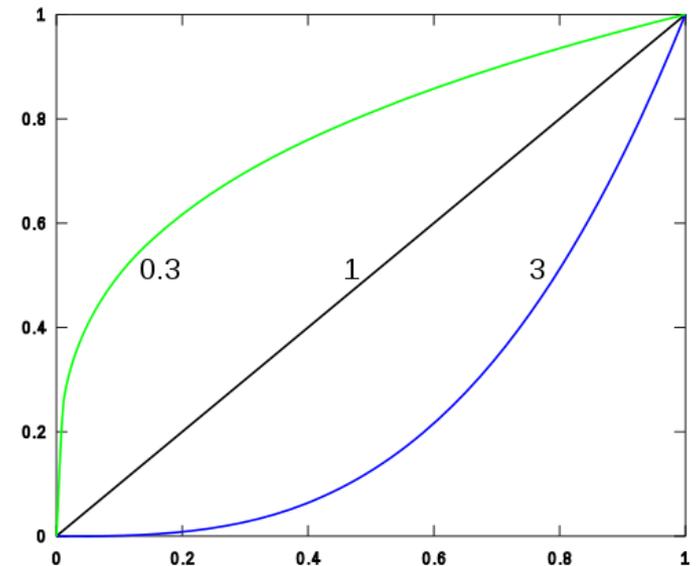
**Monitors do not emit 50% light intensity for a 50% light value (neither do our eyes work linearly)**

**Work according to a gamma function**

$$I_{out} = I_{in}^{\gamma}$$

**Monitor color space is not ideal for lighting calculations**

**Usually we choose  $\gamma = 2.2$**



More info: [http://http.developer.nvidia.com/GPUGems3/gpugems3\\_ch24.html](http://http.developer.nvidia.com/GPUGems3/gpugems3_ch24.html)

# Gamma

If images are saved non-linearly, we can encode tones better to match human vision

- Human eyes are more sensitive for differences in darker tones

**Original: Values from 0 to 1**



**Linearly encoded (using 4 bits)**



**Gamma corrected (using 4 bits)**



# Gamma correction

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## Input from gamma-corrected images

- Raise values to the power of  $\gamma$
- Note: Can be done with integer (e.g. 0 – 255) or floating point values (0.0 – 1.0)  
→ Brings colors into linear space

## Handle calculations in linear space

## Output to the monitor

- Raise output values to the power of  $\frac{1}{\gamma}$
- If needed, clamp to minimal and maximal value (e.g. 0 and 255)  
→ Brings colors into gamma-corrected space

# Sound Waves

**Air compression**

**Longitudinal Waves**

**~343 m/s**



# Sound Sensors

**Also two units**

**Infer direction by measuring time differences**

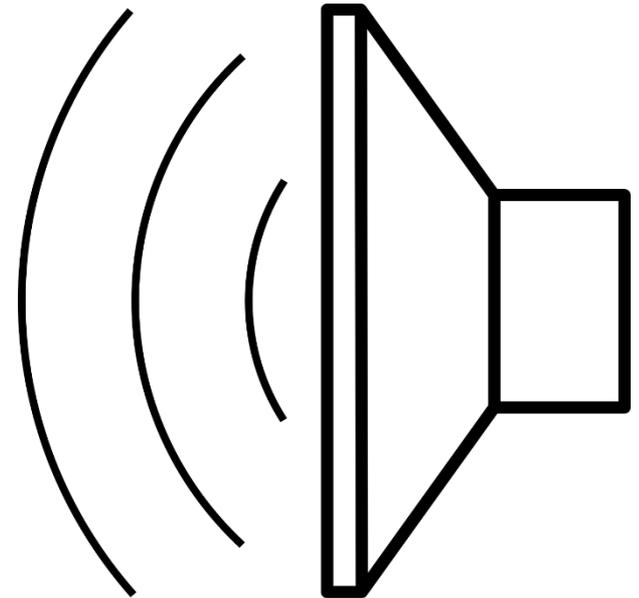
**Measure actual wave forms**



# Loudspeakers

**Construct actual sound waves**

**Physically accurate reproduction of original waves**



# Computer → Speaker

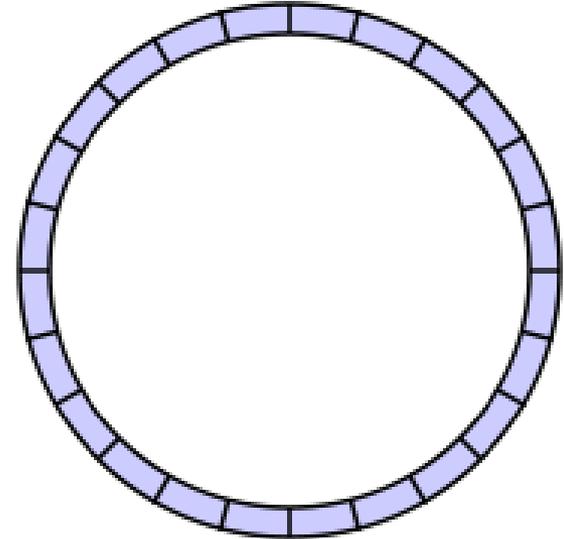
## Small ring buffer

- Write samples into the buffer
- Read back during playback

## Discretely sampled waveform

## Pointer to last sample written

## Pointer to next sample to read





# Sound Mixing

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## Superpositioning

- Adding waves

## Again physically accurate

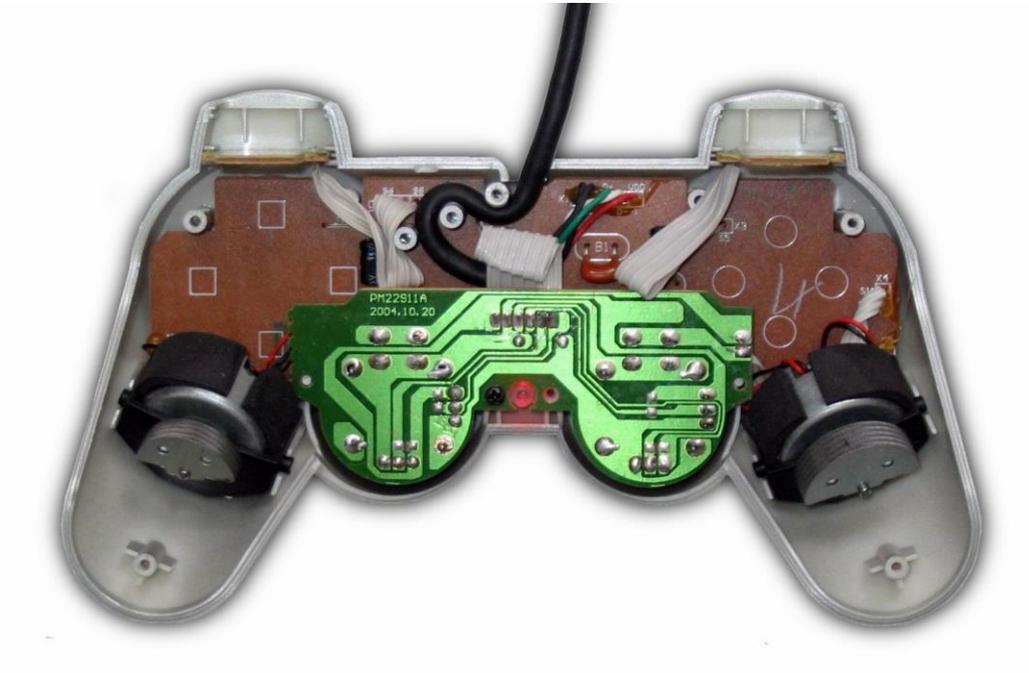
## Actual danger of superposition effects

- Avoid mixing identical sounds
- In reality, events rarely/never happen at the exact same time

# Rumble / Force Feedback



Very restricted „touch“ output



# Acceleration output



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## Sega R-360, 1991

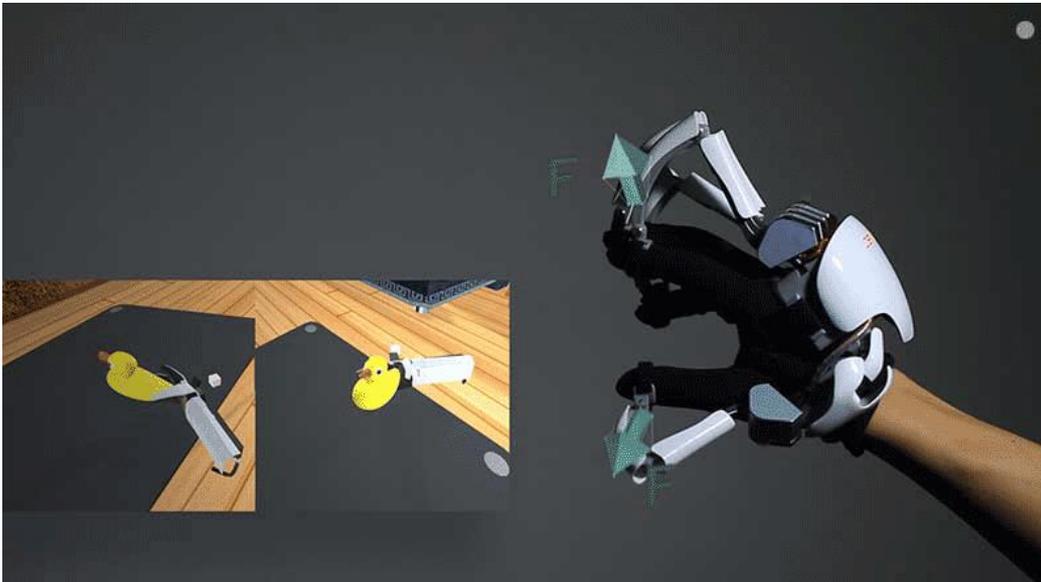


# Kinesthetic

## Virtuix Omni, 2015

## Exoskeletons

- Dexmo Glove, 2016



# Computer input



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Mouse, Keyboard, Gamepad, ...  
Mostly trivial

Important to reduce input lag

- Minimize time from input to output
- 



Nintendo Power Glove, 1989

# Complex computer input

## Input inaccuracies

- Compensate by being overly optimistic



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# Practical Part

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# C

**Portable assembler**

**Developed for/with UNIX**

**From 1969**



**Dennis MacAlistair  
Ritchie (September 9, 1941 – October  
12, 2011)**

**Open standards, not bound to a company**

**Available almost anywhere**

- Even in the browser (Emscripten/WebAssembly)



**Bjarne Stroustrup (\*30.12.1950)**

# C++

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**Adds higher level concepts to C**

**No performance regressions**

**Originally „C with classes“**

**From 1979**

# Classes



```
class Foo {  
public:  
    Foo() {  
        x = 2;  
    }  
private:  
    int x;  
};
```



# Free functions

```
int main(int argc, char** argv) {  
    return 0;  
}
```

## Main entry point

- But not on every system

## \* is a pointer

- A memory address

**char\*** is used for strings

**char\*\*** - multiple strings



# Header files

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## Using multiple source files is complicated

### Compiler compiles single cpp file to object file

- Files can **#include** other files in a preprocess
- Use separate, minimal header files for **#include**

### A separate linker application links multiple object files

No standard to tell the linker what to do

### Primary reason that compiling C/C++ is slow

# Foo.h



**#pragma once**

```
class Foo {  
public:  
    Foo();  
private:  
    int x;  
};
```

**#pragma once** is not part of the standard, but widely adopted

- Easier to write and read than other way of include guards

# Foo.cpp



```
#include "Foo.h"
```

```
Foo::Foo() {  
    x = 2;  
}
```

# C++ in 20XX

---

## Very big language

## Complex features

- Templates (similar to Java's generics) are turing complete

## Contains fancy library

- Automates memory management somewhat
- `std::string`, `std::vector`, ...

## boost Library

- Widely used
- Big, std style library

# C++ in 20XX

## Very big language

## Complex features

- Templates (similar to Java's generics) are turing complete

## Contains fancy library

- Automates memory management somewhat
- `std::string`, `std::vector`, ...

## boost Library

- Widely used
- Big, std style library



Saw comment // NEW BOOST CODE, and had a moment of panic before realizing it was vehicle boost, not C++ boost

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## Files

- That's it

## No support for

- Special directories
- Memory mapped files
- ...

# OpenGL

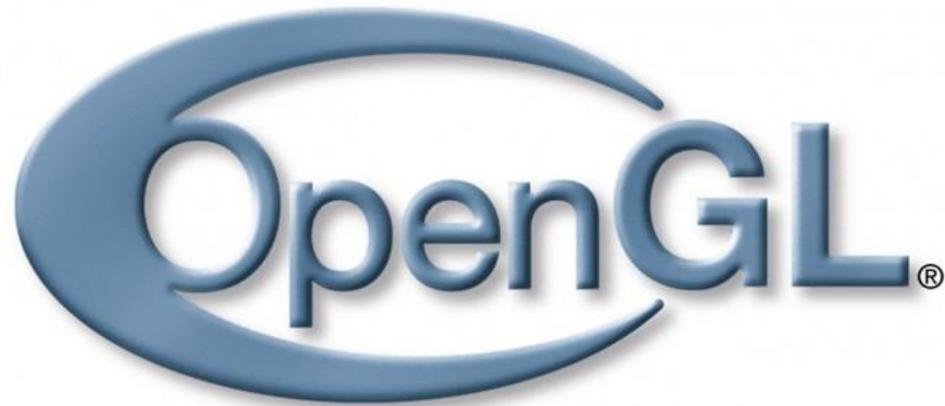
## Standard API for Graphics Hardware

### Many different versions

### Not on consoles

- In general similar to desktop variants, but specific to the capabilities of the one GPU in question

### Questionable support by Apple and Microsoft



# GPU Programming Languages

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## GLSL

- Part of OpenGL

## HLSL

- Microsoft (Direct3D and Xbox)
- Sony (all PlayStations)

## Metal

Apple

# Audio, Keyboard



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## Practically no standards

### SDL can do the job

- Simple DirectMedia Layer
- <https://www.libsdl.org/>





- **APIs for**
  - Graphics (encapsulates OpenGL and DirectX)
  - Audio
  - Input Devices
  - File Access
  - ...
- **GLSL cross compiler**
- <https://github.com/Kode/Kore>
- Introductions at <http://wiki.ktxsoftware.com>